**Assembly of circuit with MPU Gyroscope for car and sending IoT data**

**Difficulty level:** Difficult

**Goals**

Automotive IoT is the integration of gadgets, sensors, cloud computing, applications, and other such components into vehicles to function as a complex system for the connection of cars, predictive maintenance, fleet management, OEMs, insurance, and more.

The integration of the Internet of Things in the automotive industry allows manufacturers to implement sought-after innovations that can ultimately transform cars into near-artificial intelligence. At a didactic level, we are now going to develop some exercises using sensors for data acquisition, processed by the Arduino microcontroller.

**This exercise intends to apply a gyroscope guided by a microcontroller to autonomously control and correct the direction of a vehicle in the event of a skid (for example) to preserve the safety of its occupants. This exercise is aided by three LEDs that help you understand which way a possible skid is happening. It is also possible to use this type of sensor to detect the inclination of a vehicle and can autonomously assist the force to be applied to the engine in case of going uphill or help the braking system in case of going downhill.**

For the possible sending of data, it will be necessary to apply, for example, the ESP8266 ESP-01 module that allows the connection of several devices to the internet (or local network), and consequent sending of data from the sensors applied to the autonomous system.

**Image-1:** Understanding the application of MPU Gyroscope in a car and communicating with IoT.

Uma imagem com texto, diagrama, Engenharia eletrónica, Esquema

Descrição gerada automaticamente

**Image 1:** application of MPU Gyroscope in a car and communicating with IoT

**Skills**

* The skills our students will gain are:
* Students' ability to build circuits will be developed.
* The ability to program the Arduino board and use the ESP8266 Module for Internet access will develop.
* The ability to receive data from the brightness sensor and send the received data to Thing Speak will be gained.
* Data analytics will improve their ability to connect with the Internet of Things.

**Required materials and circuit diagram.**

In this exercise we intend to learn how to draw diagrams (circuits), connect all the components correctly, develop software based on C language (Arduino), connect to the wifi network, communicate with an IoT server, ThingSpeak and read server-generated graphics.

|  |  |
| --- | --- |
| **Quantity** | **Component** |
| 1 | Arduino Uno R3 |
| 1 | ESP01-8266 |
| 1 | Power Supply (braedBoard) |
| 1 | BreadBoard |
| 1 | MPU6050 |
| 3 | Led Green, Red and Blue |
| 3 | Resistor 330Ohm |

**Table 1 - Components List**

**Materials table**

|  |  |
| --- | --- |
| Arduino | ESP01 - 8266 |
| Bread Board + Power Supply | MPU6050 |
| 330Ω Leds | LCD display 2 x 16 (I2C) |
| Jumper wire | |

Uma imagem com texto, eletrónica

Descrição gerada automaticamente

**Image 2 – Diagram circuit**

**Implementation**

Development of communication of microcontroller systems, and sensors, with the ThingSpeak IoT cloud.

The ESP8266 WiFi module (image 3) is a small shield with integrated TCP/IP protocol that can give any microcontroller access to the WiFi network. The ESP8266 is capable of both hosting an application and offloading all WiFi network functions from another application processor. Each ESP8266 module is pre-programmed with an AT command making its firmware settings, meaning that we can simply connect this module to the Arduino working as any other WiFi shield would. This module has a great cost/benefit ratio and has a very large and constantly growing user community.

Uma imagem com texto, eletrónica, circuito

Descrição gerada automaticamente

**Image 3 - ESP01 – 8266**

The MPU6050 is a Micro-Electro-Mechanical Systems (MEMS) that consists of a 3-axis Accelerometer and 3-axis Gyroscope inside it. This helps us to measure acceleration, velocity, orientation, displacement and many other motion-related parameters of a system or object.

Uma imagem com texto, eletrónica, captura de ecrã, Engenharia eletrónica

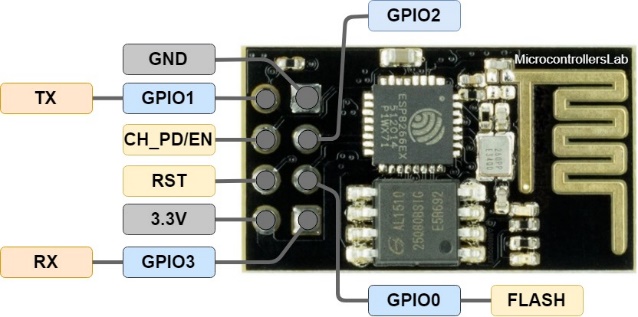
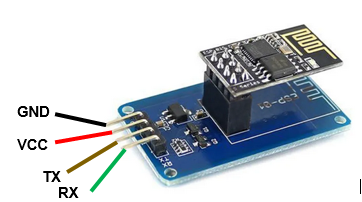
Descrição gerada automaticamente

**Image 4 MPU 6050**

**Implementation in practice**

1. Assemble the circuit in the image 2;
2. Connect correctly ESP01-8266 image 5

**Image 5** ESP-01 Connections



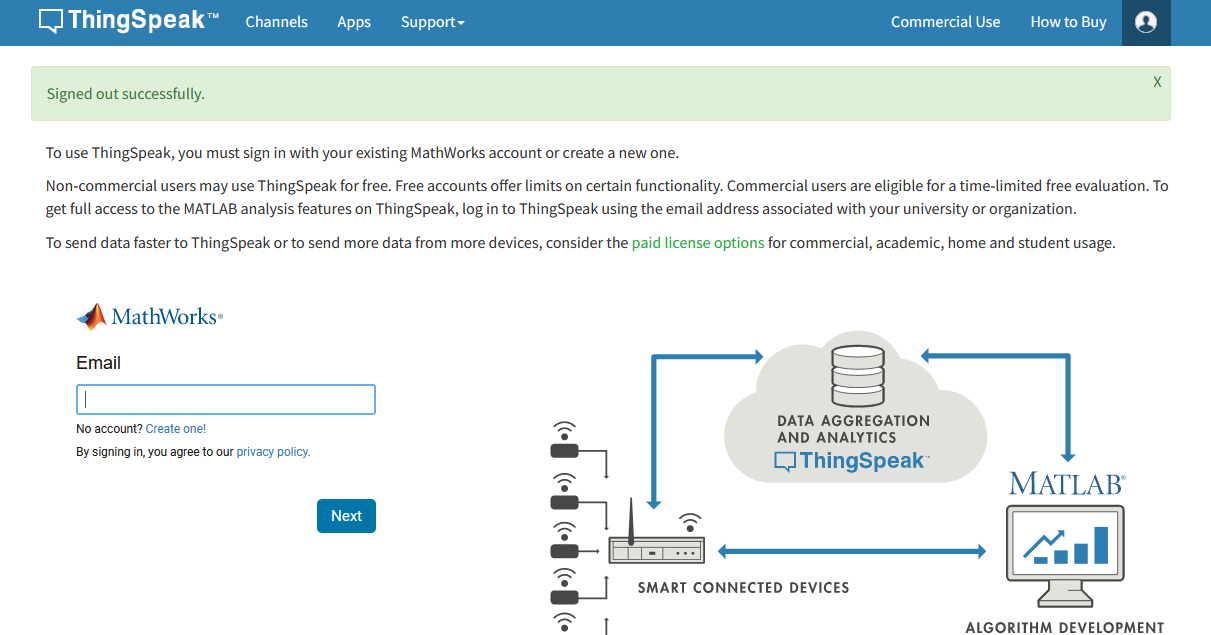
1. Real assembled circuit image 6

Uma imagem com eletrónica, Engenharia eletrónica, Componente de circuito, circuito

Descrição gerada automaticamente

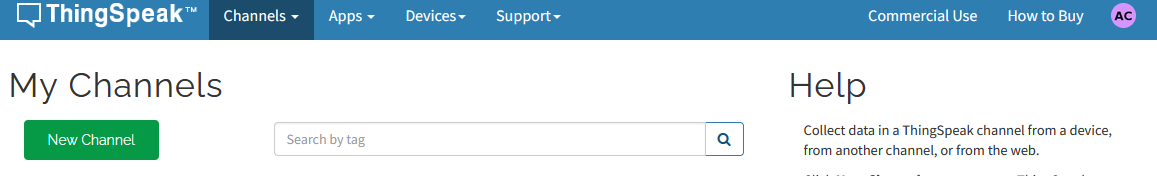
**Image 6** Real circuit in breadboard

1. Create a ThingSpeak account image 7



**Image 7 - Thing Speak**

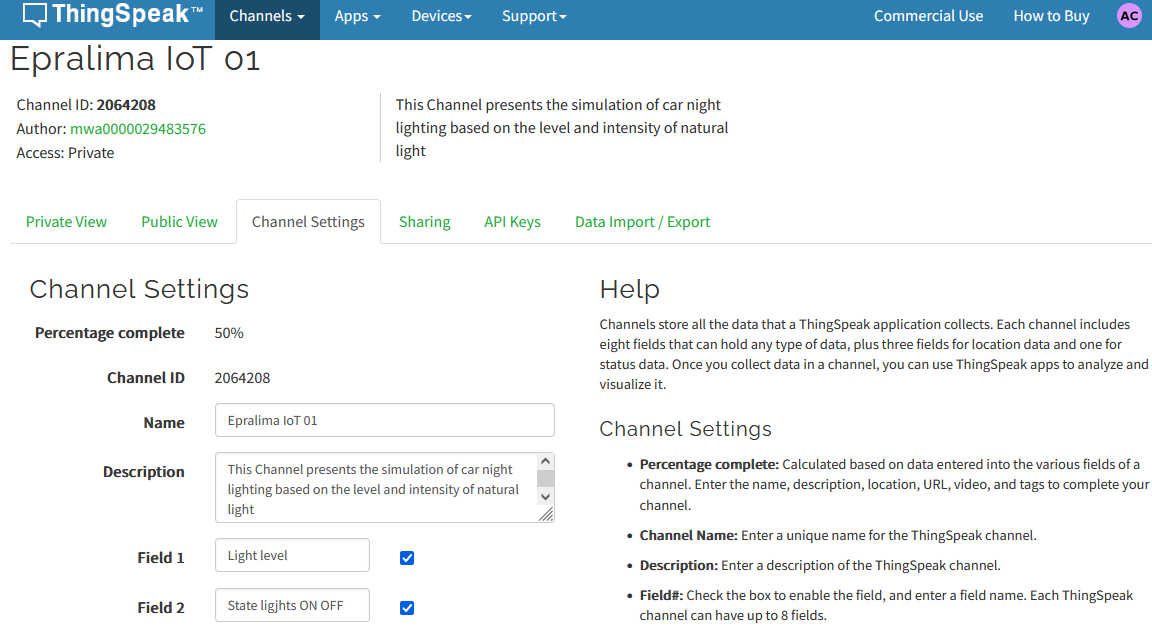
1. Create a new channel image 8



**Image 8 Interface ThingSpeak**

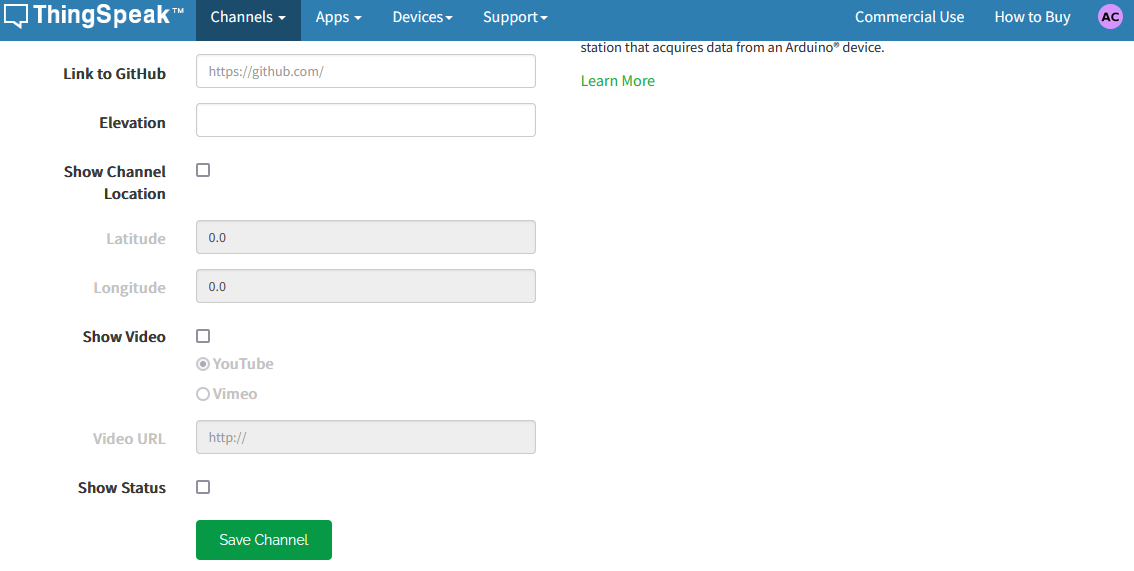
1. Configure channel, with name, description, and fields. Image 9.

**Note:** The fields refer to data processed by the microcontroller and data from the sensors under study. Each field will generate a graph.



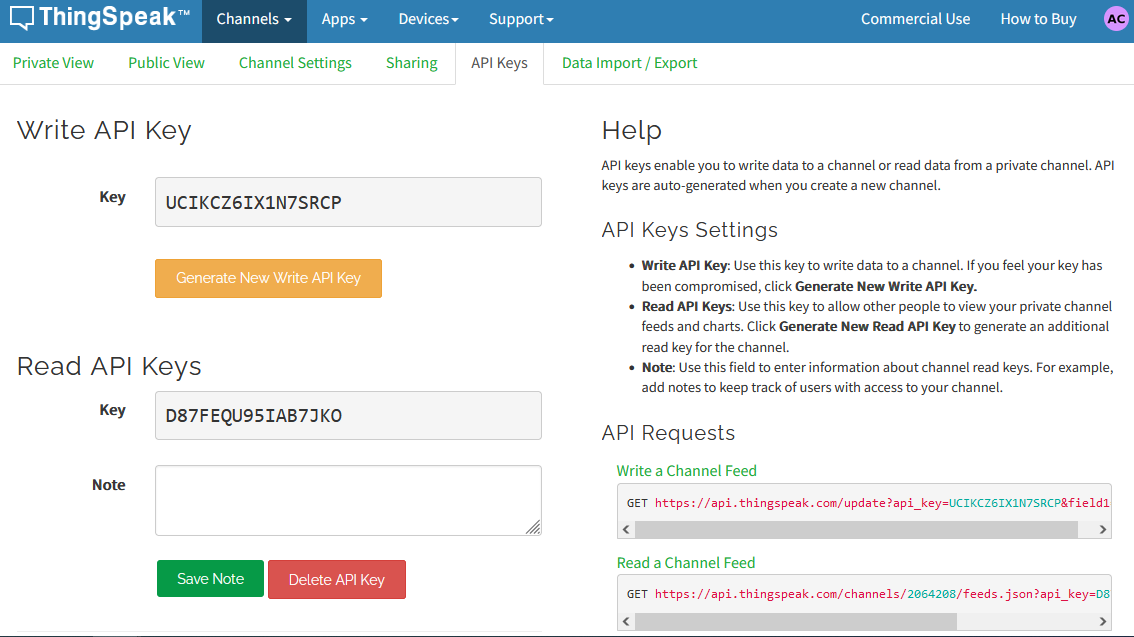
**Image 9 Configure Channel**

1. Save settings channel Image 10



**Image 10 Save settings channel**

1. In this step, we will pay special attention to the api keys, as they are the ones that, through the string key, will allow access to the IoT repository in Arduino programming. Also very important are the API requests.



**Image 11 - API Keys**

1. Programming Arduino

Inclusion of the necessary libraries and declaration of variables and constants inherent to the program's operation.

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Descrição gerada automaticamente

Void setup() function for initializing parameters for starting the program.

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Descrição gerada automaticamente

**AT commands**

AT commands are the basic way to configure and trigger the ESP8266 when it is under control of an external device (like an Arduino, for example).

Current AT commands are direct descendants of the so-called "Hayes Standard" from 1981, used to allow personal computers to interact with telephone connections by directly controlling a mode.

The **InitWifiModule()** function initializes the ESP8266 through AT commands.

Uma imagem com texto

Descrição gerada automaticamente

The **envioDadosESP\_AT(str,int,boolean)** function is responsible for sending AT commands to the ESP8266

Uma imagem com texto

Descrição gerada automaticamente

The **startThingSpeakCmd(str,int,boolean)** function opens connection to ThingSpeak IoT analytics platform. The IP address of the ThingSpeak platform is: 184.106.153.149 with connection on port 80. The AT command to start ThingSpeak communication is AT+CIPSTART=PROTOCOL, IP\_ADRESS, PORT.

Uma imagem com texto

Descrição gerada automaticamente

The **EscreverParaThingSpeak** function generates a string to build an API Request.

**Example:**

**GET /update?api\_key=U………….P&field1= 0&field2= 0**

Uma imagem com texto, captura de ecrã, Tipo de letra, número

Descrição gerada automaticamente

The **GetThingSpeak(str)** function, is responsible for determining and sending an API Request through the AT+CIPSEND command to write to the ThingSpeak channel, returning the message received by the response from the ThingSpeak data platform. The communication will be closed if the response is not favourable.

Uma imagem com texto

Descrição gerada automaticamente

The **inclinationUP\_DOWN(), inclinationRIGHT\_LEFT() and rotation()** These procedures update the angle of the MPU 6050 module.

Uma imagem com texto, captura de ecrã, Tipo de letra, número

Descrição gerada automaticamente

Uma imagem com veículo, Veículo terrestre, esboço, roda

Descrição gerada automaticamente

**inclinationUP\_DOWN()** Pitch

**inclinationRIGHT\_LEFT()** Roll

**rotation** Yaw

**Results**

In the analysis of the graphs, it is possible to observe that there was a negative angle that could mean that a car could be making a downhill road. It is possible to verify that there was a variation in the inclination of the car, which means that the road may have a small inclination in roll. It is possible to analyse the number of curves made by a car.

Uma imagem com texto, diagrama, captura de ecrã, Tipo de letra

Descrição gerada automaticamente

**Image 12 – Results IoT ThingSpeak**

The data acquired by the ThingSpeak IoT platform can also be exported to CSV files and consequently imported into datasheets as shown in Table 2

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Descrição gerada automaticamente

**Tabela 2 - DataSheet**

**In short**

This exercise intends to apply a gyroscope guided by a microcontroller to autonomously control and correct the direction of a vehicle in the event of a skid (for example) in order to preserve the safety of its occupants. This exercise is aided by three LEDs that help you understand which way a possible skid is happening.

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